

# 1.2 Row Reduction and Echelon Forms

**Nooshin Maghsoodi**

Noshirvani University

These slides are adapted from Linear Algebra course in UESTC

# Outline

- 1 Echelon Forms
- 2 Pivot Positions
- 3 Row Reduction Algorithm
- 4 Solutions of Linear Systems
- 5 Existence and Uniqueness Questions

## A few definitions:

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- **leading entry**: the leftmost nonzero entry (in a nonzero row)

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- 2 Each leading entry of a row is in a column to the right of the leading entry of the row above it.
- 3 All entries in a column below a leading entry are zeros.

# Reduced Echelon Form (RREF)

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- ④ The leading entry in each nonzero row is 1.

# Reduced Echelon Form (RREF)

## Reduced echelon form

- 4 The leading entry in each nonzero row is 1.
- 5 Each leading 1 is the only nonzero entry in its column.

# Echelon Form

$$\begin{bmatrix} \blacksquare & * & * & * \\ 0 & \blacksquare & * & * \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix},$$

$$\begin{bmatrix} 0 & \blacksquare & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & \blacksquare & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & \blacksquare & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & \blacksquare & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \blacksquare & * \end{bmatrix}$$

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## Reduced Echelon Form

$$\begin{bmatrix} 1 & 0 & * & * \\ 0 & 1 & * & * \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix},$$

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## Echelon Form

$$\begin{bmatrix} \blacksquare & * & * & * \\ 0 & \blacksquare & * & * \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \quad \begin{bmatrix} 0 & \blacksquare & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & \blacksquare & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & \blacksquare & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & \blacksquare & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \blacksquare & * \end{bmatrix}$$

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A matrix in (reduced) echelon form is called a **(reduced) echelon matrix**.

# Echelon Form

Are the following matrix in (reduced) echelon form?

1 
$$\begin{bmatrix} 0 & -1 & 2 & 0 \\ 1 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

2 
$$\begin{bmatrix} 0 & -1 & 2 & 0 \\ 0 & 0 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

3 
$$\begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

4 
$$\begin{bmatrix} 1 & -1 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

# Recall: row equivalent

## Three elementary row operations

- 1 **Replacement** Replace one row by the sum of itself and a multiple of another row.
- 2 **Interchange** Interchange two rows.
- 3 **Scaling** Multiply a row by a **nonzero** constant.



If a matrix  $A$  is row equivalent to an echelon matrix  $U$ , we call  $U$  **an echelon form** (or row echelon form) of  $A$ ; if  $U$  is in reduced echelon form, we call  $U$  **the reduced echelon form** of  $A$ .

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### Uniqueness of the **RREF**

Each matrix is row equivalent to one and **only one** reduced echelon matrix.

## Pivot Position and Pivot Column

A **pivot position** in a matrix  $A$  is a location in  $A$  that corresponds to a leading 1 in the reduced echelon form of  $A$ . A **pivot column** is a column of  $A$  that contains a pivot position.

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## Example

Reduce the matrix to REF, then RREF

$$A = \begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$

# The Row Reduction Algorithm

- 1 Begin with the **leftmost nonzero column**. This is a pivot column. The pivot position is at the top.
- 2 Select a **nonzero entry in the pivot column as a pivot**. If necessary, interchange rows to move this entry into the pivot position.
- 3 Use row replacement operations to **create zeros** in all positions below the pivot.

# The Row Reduction Algorithm

- 4 Repeat the process until there are no more nonzero rows to modify.
- 5 Beginning with the **rightmost pivot** and working upward and to the left, create zeros above each pivot. If a pivot is not 1, make it 1 by a scaling operation.

## Example

Apply elementary row operations to transform the following matrix first into echelon form and then into reduced echelon form

$$\begin{bmatrix} 0 & 3 & -6 & 6 & 4 & -5 \\ 3 & 11 & 8 & -5 & 8 & 9 \\ 3 & 9 & 12 & -9 & 6 & 15 \end{bmatrix}$$

# Solutions of Linear Systems

## Important facts

- A linear system corresponds to **a unique augmented matrix** and vice versa.



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- A linear system corresponds to **a unique augmented matrix** and vice versa.
- Row reduction **does not change** the solution set.

# Solutions of Linear Systems

## Example

The equivalent RREF of the augmented matrix of a

linear system  $\begin{bmatrix} 1 & 0 & -5 & 1 \\ 0 & 1 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

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- **basic variable**: the variables corresponding to pivot columns in the matrix.

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## Example

The equivalent RREF of the augmented matrix of a

linear system 
$$\begin{bmatrix} 1 & 0 & -5 & 1 \\ 0 & 1 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

- **basic variable**: the variables corresponding to pivot columns in the matrix.
- **free variable**: the other variables.

## Existence and Uniqueness Theorem

A linear system is consistent **if and only if** an echelon form of the augmented matrix has no row of the form

$$[0 \quad \cdots \quad 0 \quad b] \quad \text{with } b \text{ nonzero}$$

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If a linear system is consistent, then the solution set contains either

- 1 a unique solution, when there are no **free variables**, or
- 2 infinitely many solutions, when there is at least one free variable

## Example

Find the general solution of the linear system whose augmented matrix is

$$\textcircled{1} \begin{bmatrix} 1 & 0 & -5 & 1 \\ 0 & 1 & 1 & 4 \\ 1 & 1 & -4 & 5 \end{bmatrix}$$

$$\textcircled{2} \begin{bmatrix} 1 & 6 & 2 & -5 & -2 & -4 \\ 0 & 0 & 2 & -8 & -1 & 3 \\ 1 & 6 & 4 & -13 & -2 & 6 \end{bmatrix}$$